

GREENSPAN



# MP/MQ Series

Multi-Parameter Water Quality Sensors

## PRODUCT USER MANUAL



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# 1 Introduction

## 1.1 System Description

Thank you for purchasing a GreenSpan MQ/MP Series Sensor (Model MP47 or MQ65). This manual provides a guide to the configuration, operation and maintenance of your sensor to provide long term reliable and accurate monitoring.

The GreenSpan MQ/MP Series sensors provide a complete self-contained measurement and data logging system for a wide range of environmental water monitoring applications. The sensors provide the ability to measure single or multiple water quality parameters (up to 4 parameters on the MP47 and 6 parameters on the MQ65) within the single sensor providing users the choice to select the parameters which best suits their application.

Users have a choice of the following parameters:

- Pressure
- pH
- Oxygen Reduction potential
- Electrical Conductivity
- Temperature
- Turbidity
- Optical Dissolved Oxygen

The sensor includes an internal data logger to provide long term data collection at remote sites. A large memory capacity (4 Mb) allows the MQ/MP Series Sensor to store data over long periods before being downloaded either locally or remotely by your preferred communications method.

Communication with the MQ/MP Series Sensor is user selectable RS232 or RS422/485. Set up, data collection and other user functions are simple to access using the supplied software package. Additionally key sensor information and control is available via MODBUS. Sensors are also compatible with the optional SDI-12 adapter.

The MQ/MP Series Sensor can be powered using external batteries (via the sensor cable) or with GreenSpan's Optional Lithium battery pack, which can be fitted as an extension to the sensor body, making it a fully self-contained measurement and logging system.

## **1.2 Certification**

The MQ/MP Series sensors are assembled and tested in accordance with GreenSpan's ISO 9001 Quality Certified System. Each Sensor is individually manufactured and certified against a traceable Standard.

Following calibration the sensors undergo a range of additional control processes to ensure that all specifications are consistent and documented.

- The instrument is visually inspected, marked and labelled.
- The complete sensor calibration record is archived for reference, and batch number information is kept on file for statistical analysis.
- An individual Certificate of Conformance is issued to the customer.

### 1.3 Unpacking and Inspection

All GreenSpan sensors are made to order and are individually calibrated and inspected. This ensures that they leave the factory in a working condition. They are packed in new cartons for shipping. On receipt, the customer should inspect the packaging and contents for any signs of damage during transportation. The customer should also check that all items on the delivery note have been received.

Please contact the factory in case anything has been damaged or missing. A full set of documentation including Certificate of Conformance, Quick Start Guide, and User Manual will be provided with all equipment – either in hard copy format or in electronic format on the USB flash memory device shipped with the goods.

Care should be taken against possible corrosion in high Chloride or Ferric solutions, water with high iron or sulphate reducing bacteria, or low dissolved oxygen. The sensor can be fitted with an Acetal body which provides superior corrosion protection in a wide range of chemically active waters.

Because an individual sensor may be used in a variety of locations, media compatibility should be checked before installing and advice sought from GreenSpan if any doubt exists.

### 1.4 Serial Number

Checking the Model Number and Range

Before installing your GreenSpan MQ/MP Series sensor, check the information on the label is correct to confirm you have received the instrument you have ordered. The label will look similar to this.

*For MP47:*

<b>MODEL</b>	<b>MP47</b>
<b>RANGE</b>	<b>0 – xx M</b>
<b>OUTPUT</b>	<b>RS232</b>
<b>S/N</b>	<b>012345</b>

*For MQ65:*

<b>MODEL</b>	<b>MP47</b>
<b>RANGE</b>	<b>0 –14pH 0 - xx M</b>
<b>OUTPUT</b>	<b>RS232</b>
<b>S/N</b>	<b>012345</b>

Please note, where sensors have been supplied with two or more parameters, the range of each parameter will be noted on the serial number label. The ranges may be listed in no specific order. The customer is advised to keep a record of the serial numbers in case the sensor is lost or damaged. GreenSpan keeps records of all sensors sold including a calibration history.

## **1.5 Warranty Policy**

GreenSpan warrants all new GreenSpan products against defects in materials and workmanship for **12 months** from the date of invoice.

Products that prove to be defective during the warranty period will be repaired or replaced at the discretion of GreenSpan.

Under GreenSpan warranty conditions; it is the responsibility of the customer to cover shipping charges back to the factory. Upon repair/replacement GreenSpan will cover the return shipping charges to the customer.

This warranty does not apply to products or parts thereof which have been altered or repaired outside of the GreenSpan factory or other authorised service centre; or products damaged by improper Installation or application, or subjected to misuse, abuse neglect or accident. This warranty also excludes items such as reference electrodes and Dissolved Oxygen membranes that may degrade during normal use.

GreenSpan will not be liable for any incidental or consequential damage or expense incurred by the user due to partial or incomplete inoperability of its products for any reason whatsoever or due to inaccurate information generated by its products.

All Warranty service will be completed as soon possible. If delays are unavoidable customers will be contacted immediately.

Any sensor should not be dismantled unless under instruction from GreenSpan Service staff. Incorrect handling will void the warranty.

## **1.6 Factory Service & Repair**

If for some reason sensors are required to be returned to our factory or your sales representative, please note the model and serial number, describe the problem, including how and under what conditions the instrument was being used at the time of malfunction. Clean the product and cable. Decontaminate thoroughly if used in toxic or hazardous environment. Carefully pack product in original packaging if possible & include a statement certifying product and cable have been decontaminated with supporting information. Products returned for repair must be accompanied by a completed GRN (Goods Return Notification) form. All sensors returned for service and repair work must be properly decontaminated prior to return. A cleaning charge may be applied to sensors that require further decontamination. Service work will not commence until the quotation has been accepted by the customer. A purchase order for all repair and service work will be required before work is carried out.

## 2 Sensor Overview (by Parameter)

### 2.1 Pressure



The pressure sensor utilises a ceramic-based, capacitive element as the transducer. This is designed to be of rugged construction and incorporates active electronics as an integral part of the transducer substrate to enhance reliability and accuracy. Force applied to the ceramic element, due to the pressure, deforms its shape. This deformation causes a change in capacitance which can be measured by the electronics. The inherent stability and toughness of the ceramic ensures the repeatability and long term accuracy of the readings are maintained under the harshest eld conditions.

The on-board microprocessor converts the transducer output voltage to a 24 bit digital signal and also measures the transducer temperature. This information is used to temperature compensate the sensor over the range 0 - 50°C. Both pressure and temperature are displayed in SensorMate in real units i.e. metres of depth and degrees Centigrade.

Benefits of the ceramic capacitance sensors over other types of sensors are:

- Extremely high overload limit (typically up to 10 X overload protection)
- Absolute resistant to wear
- High temperature stability
- Excellent Long term stability
- Excellent Repeatability and linearity
- No hysteresis effects normally associated with strain type sensors
- Corrosion resistant – Other sensors require contact of stainless steel face
- Not subject to mechanical fatigue that may affect strain gauge type sensors
- Low power consumption suitable for remote monitoring & control units

#### 2.1.1 *Absolute or Gauge*

Gauge sensors are vented to atmosphere so that the effects of changes in barometric or atmospheric pressure do not affect water level readings. Sensors that are not vented to atmosphere are referred to as Absolute Sensors. The primary difference between the two types of sensors is the effect of atmospheric pressure on the water level measurements they provide.

Barometric Pressure acts on both sides of a Gauge sensor (i.e. via the water on one side and via the vent tube on the other). The Barometric pressure is cancelled out and has no effect on the water level readings. Gauge Sensors will read zero in air.

Barometric atmospheric pressure acts only on one side of a non-vented or Absolute Sensor (on the water side). Any changes in Atmospheric pressure will be detected by the sensor and measured as changes in water pressure. As the Barometric pressure varies, these changes will be measured as water level changes even though the actual water level may have remained steady. Typical variations in barometric pressure when converted to head of water are in the order of +/- 100mm. A large change in weather pattern (storm front) may cause a drop in barometric pressure by up to 20Hpa

which would cause an error of 200mm. Water level variations caused by barometric pressure can be removed by monitoring barometric pressure (e.g. via a weather station or barometric sensor) and then post processing the absolute water level readings.

The lowest, standard absolute range offered is 20m, which is suitable for measuring water levels of up to approximately 10m. Absolute sensors will read zero in a perfect vacuum and around 10m in air depending on the atmospheric pressure.

Gauge sensors are suitable for most monitoring applications where water level readings are required. Absolute sensors are suitable for applications where a vented cable is not desirable (e.g. Battery pack only sensors).

### **2.1.2 Moisture Ingress**

To avoid moisture ingress via the vent tube on any sensor configuration with gauge pressure sensors, a closed vent system is provided which maintains atmospheric pressure within the ceramic capacitance transducer while preventing moisture condensing within the sensor cable.

## **2.2 Electrical Conductivity (Toroidal Sensing Head)**



The EC sensor uses an electromagnetic field for measuring Conductivity. The black plastic head contains two coils wound on toroidal (i.e. doughnut shaped) ferrite cores. The hole in the EC head passes through the centre of the coils. One Coil is excited with an alternating current which generates an electromagnetic field around the coil and into the water. Special electronics senses the amount of electromagnetic field in the second coil which is proportional to the Conductivity of the water that fill the hole and surrounds the head.

The main benefit derived from utilising toroidal sensing technology for the measurement of EC is the reduction in fouling and the elimination of system errors caused from electrode degradation. There are no electrodes in direct contact with the water that can foul, erode or corrode. The sensor head should be periodically inspected and cleaned with fresh water and damp cloth. The protective shroud is easily unscrewed from the head for quick access. Brushes are commonly used for cleansing the sensor hole. In marine environments crustaceans may need removal at regular intervals.

The toroidal sensors create a magnetic field around the sensing head. The standard EC sensor includes a shroud around the transducer head that constrains this field and allows the sensor to be deployed close to other objects. The sensor head should always be completely submerged and positioned such that the possibility of air bubbles becoming entrapped within the sensor hole is minimised. Large bubbles may cause errors if trapped.

Electrical Conductivity (EC) is the measurement that indicates the ability of a solution to carry an electric current. It is defined as the inverse of resistance (Ohms) per unit square and is measured in units of Siemens/metre or micro-Siemens/centimetre.

EC readings are a function of the number of ions present and their mobility. The electrical Conductivity of a liquid changes due to the ion mobility being temperature dependant. The temperature co-efficient of conductance (or the K factor) varies for different salts and can be in the range 0.5 to 3.0. A default value of 1.84% per degree Centigrade is used in the MQ/MP Series sensors.

EC is a function of both salt concentration and temperature, and its value can be expressed as non-normalised or normalised. The non-normalised (Raw) reading will vary with temperature even if the concentration of salt in the liquid does not change. Normalisation automatically compensates for temperature variations providing the salt concentration remains the same. Normalisation is referenced to 25°C which means that the raw and normalised readings are identical at this temperature.

The measurement of Conductivity is usually carried out to assist in the determination of the salt content of a water body (the salinity). The MQ/MP Series sensor calculates a salinity value, based on method "2530-D, Algorithm of Practical Salinity" (Standard Methods for the Analysis of Water and Wastewater). This method is also contained in "UNESCO Technical papers in marine science 44 – Algorithms for computation of fundamental properties of seawater."

## 2.3 pH



The PH sensor uses a robust, gel filled, industrial pH electrode for field monitoring in a variety of environments.

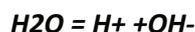
The pH electrode consists of a PH sensitive glass membrane attached to a sealed insulating tube containing a solution of fixed PH in contact with a silver-silver chloride half cell. The potential developed across the membrane is compared to a stable reference potential e.g. a silver-silver chloride half-cell in contact with an electrolyte containing chloride. Completion of the circuit is by means of a porous constriction (the salt bridge) which allows the reference electrolyte to slowly flow into the sample.

pH gives an indication of the acidity/alkalinity of a solution and is defined as:

$$pH = -\log (H^+)$$

and covers a scale from 0 (acid) to 14 (alkaline) where H<sup>+</sup> is the hydrogen concentration in solution, at ordinary temperatures.

E.g. pH of water



The concentration of each type of ion is 10<sup>-7</sup>gm molecule/litre and hence the pH of pure water is:

$$pH = -\log 10^{-7} = 7$$

## 2.4 ORP



The principle means of detection is by measuring the difference in potential between an inert indicator electrode and a reference electrode. At redox equilibrium, the potential difference between the ideal indicator electrode and the reference electrode equals the redox potential of the system.

Reactions involving ions are both pH and Eh(mV) dependent, therefore chemical reactions in aqueous media can often be characterised by pH and Eh acting together with the activity of dissolved chemicals. The MQ/MP Series sensor

probe uses a combination, Platinum ORP and reference electrode in the one body. This electrode is field replaceable by the user. Electrodes made of Platinum are most commonly used for Eh measurements. The standard hydrogen reference electrode is fragile and impractical for routine field use. The GreenSpan ORP sensor uses a silver:silver-chloride electrode and these are commonly used.

The reference consists of a specially coated wire in a salt filled cavity. This cavity makes electrical contact with the outside aqueous solution through a small porous wick. A common cause for premature ORP sensor failure is the chemical or biological contamination or fouling of the wick or salt filled cavity. Added protection for the reference electrode is provided by a reference protection ring constructed of porous PTFE that is impregnated with a special conductive gel. It is placed over the reference wick and should prevent most contaminants from reaching the wick, while still allowing good electrical contact with the sample. If the low cost protection ring is contaminated or fouled it can be simply replaced, extending the life of the combination electrode.

## 2.5 Turbidity



Turbidity is the measurement that indicates the clarity of water due to fine suspended particles. In the environment, turbidity is often due to clay or silt. These fine particles have the ability to scatter light. The MQ/MP Series sensor has a light source that is projected into the water. A detector measures the light that has been scattered at 90 degrees to the source. As the number of particles increase, more light is scattered and sensed by the detector and the higher the turbidity reading.

The Turbidity probes, with their integral wiper assembly, are designed where bio-fouling or sedimentation build-up is possible. The probes may be submerged to a depth of 1 meters (approx. 330 feet).

The MQ/MP Series Sensors use 90° optics and employs infrared light in accordance with ISO7027. The Optical system transmits a beam of 860nm wavelength. The effective working area around the sensor is approximately 50mm forward and 50mm circumference. The sensor uses a unique modulation technique that ensures almost total rejection of ambient light conditions as well as a unique microprocessor controlled

sample and hold circuit for enhanced performance particularly at low turbidity levels.

## 2.6 Optical Dissolved Oxygen



The optical dissolved oxygen (ODO) sensor uses a robust, solid state, fluorescence based transducer for field monitoring in a variety of environments. Fluorescence based sensors are inherently reliable and low maintenance, with no need for replaceable membranes or electrolyte. No Oxygen is consumed during operation making the sensor suitable for low flow applications. The sensor also responds

quickly to changes in Oxygen levels.

### **2.6.1 Principal of Operation**

- The emitter sends light, at ~475 nm, to the back side of the sensing element.
- The wetted side of the sensing element consists of a thin layer of a hydrophobic sol-gel material. A ruthenium complex is trapped in the sol-gel matrix, effectively immobilized and protected from water.
- The light from the LED excites the ruthenium complex immobilized in the sensing element.
- The excited ruthenium complex fluoresces emitting energy at ~600 nm.
- If the excited ruthenium complex encounters an oxygen molecule, the excess energy is transferred to the oxygen molecule in a non-radiative transfer, decreasing or quenching the fluorescence signal (see Fluorescence Quenching below). The degree of quenching correlates to the level of oxygen concentration in contact with the sensing element.

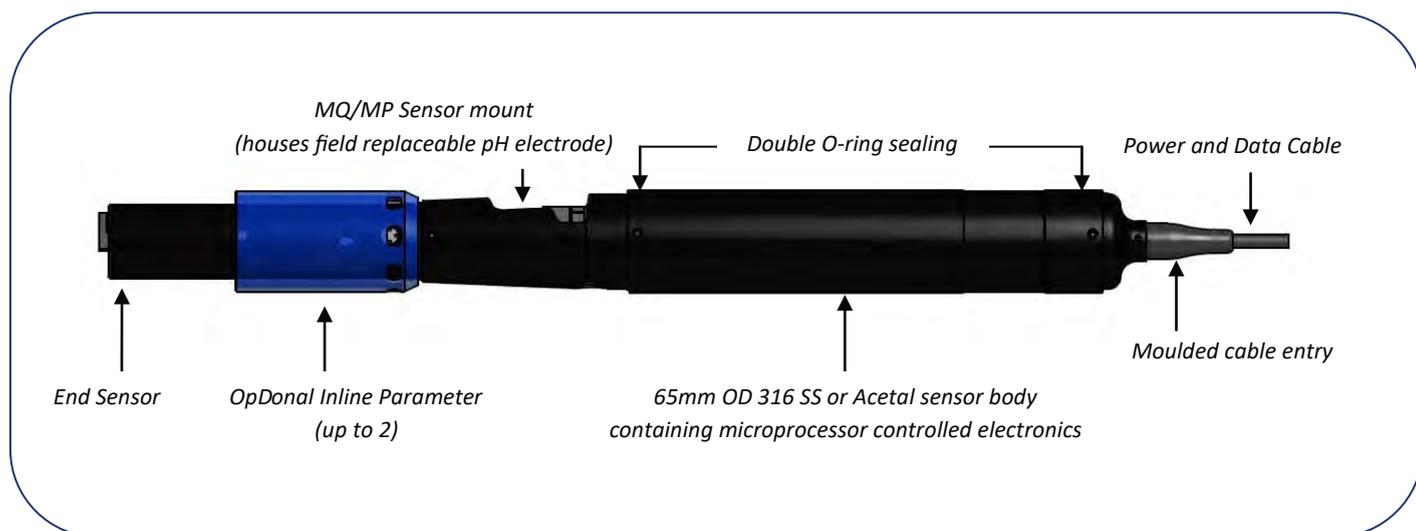
### **2.6.2 Fluorescence Quenching**

Oxygen is able to efficiently quench the fluorescence and phosphorescence of certain luminophores. This effect (first described by Kautsky in 1939) is called "dynamic fluorescence quenching." Collision of an oxygen molecule with a fluorophore in its excited state leads to a non-radiative transfer of energy. The degree of fluorescence quenching relates to the frequency of collisions, and therefore to the concentration of the oxygen-containing media.

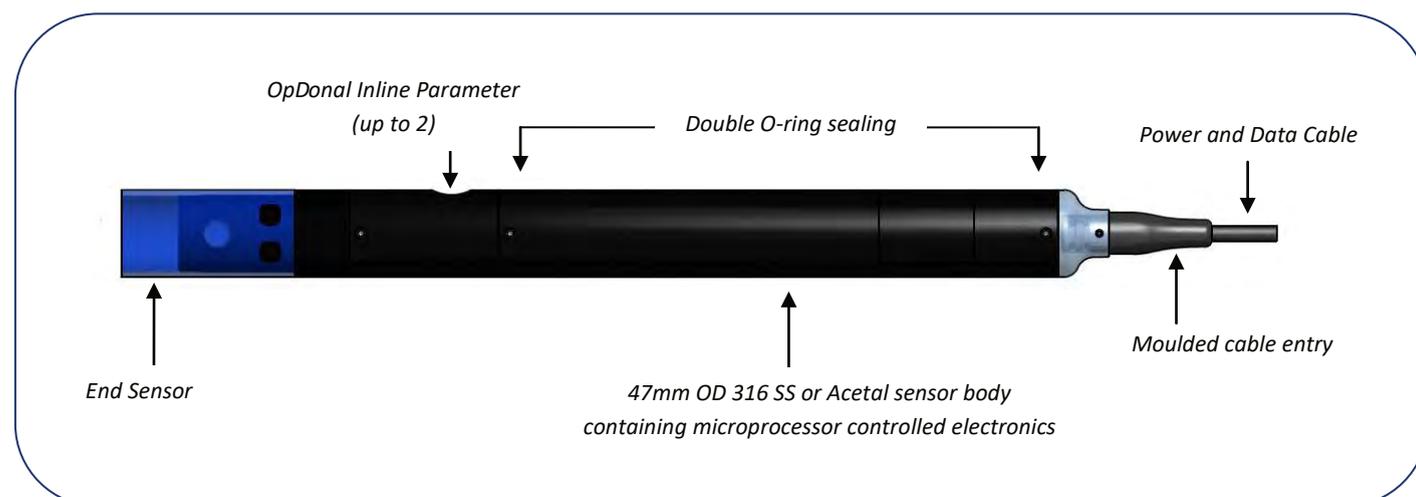
## 4 Instrument Details

### 4.1.1 Sensor Design

The GreenSpan MQ65 Sensor consists of the following primary elements:



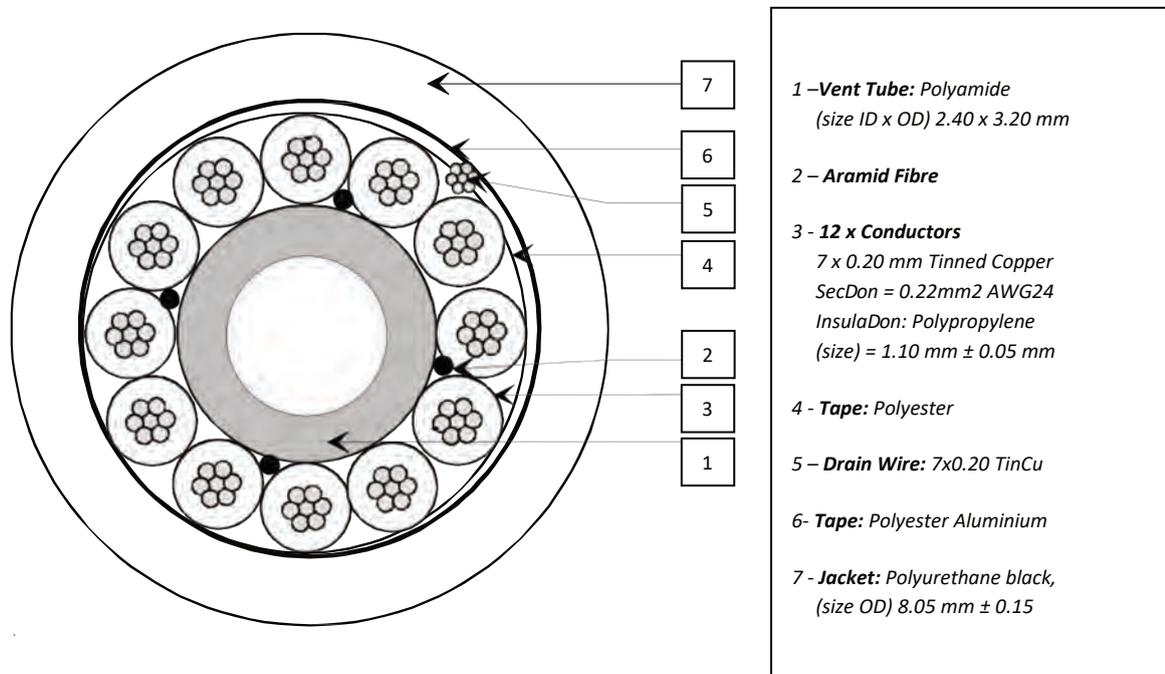
The GreenSpan MP47 Sensor consists of the following primary elements:



#### 4.1.2 Cable Details

All GreenSpan sensors utilise a specially designed Polyurethane Cable. The cable is reinforced with Aramid fibre which provide superior tensile strength and low stretch properties. Changes in temperature have little effect on the overall length of the cable. This feature provides users with the benefit of self-suspending the sensor to depths of 300m without additional strain relief.

The cable contains 12 x conductors, 1 x drain wire, an internal vent tube and Aramid fibres. The outer jacket is made from UV stabilized Polyurethane and is suitable for all external, underwater or harsh environment applications. This common cable construction is utilised for vented and non-vented GreenSpan sensors. Cables are generally factory fitted at time of manufacture in specific lengths.



#### 4.1.3 Mechanical Specifications

- Specially manufactured GreenSpan cable with 12 cores and internal vent
- High chemical resilience and abrasive resistance
- Conductor cross section : AWG 24,
- Electrical Resistance 9 ohm per 100m (per conductor)
- Operating temperature: 85°C (max.),
- Bending radius (static) : 6 ,
- Bending radius (dynamic) 12.
- Max Operating voltage : 250V
- Jacket Printing (white colour each meter)
- Conductor colour codes : green, yellow, white, black, brown, turquoise, violet, pink, red, blue, grey

The moulded cable is fitted to the sensor using a double o ring seal and located using 2 x grub screws. The length of the cable is not critical to the long term calibration and operation of the sensor (provided the electrical requirements such as minimum supply voltage are maintained).

## 4.2 Options and Accessories

### 4.2.1 Closed Venting System (CVS)



When MQ/MP sensors (configured with a depth sensor) are deployed, there can be a difference between the atmospheric temperature and the temperature of the sensor at depth.

This temperature differential causes a pumping effect to occur whereby moist air from the surface is drawn into the sensor through the vent line. This moisture can condense on sensitive electronic components due to warm surface air cooling inside the sensor.

Sealing the system against exposure to the atmosphere and conditioning the existing air in the vent tube can alleviate this problem. Silica desiccant crystals easily absorb moisture thereby drying the air and are used in the closed loop venting system **7CVS-001**.

For all gauge (vented sensors) a Closed Vent System must also be fitted (pictured left). A single 7CVS-001 is designed to handle sensor cable lengths up to **70 metres**. Multiple units may be joined together for greater capacity. Please refer to the Engineering Note in the appendix section on the manual for detailed instructions on the installation of the 7CVS-001. Dimensions (including filter) length x width x height 16cm x 7cm x 5cm.



### 4.2.2 Protective Nose Cones

A protective copper nose cone (*GreenSpan Part # 492-0241*) can be fitted to the pressure transducer (end sensor configuration only) to inhibit biological or marine growth on the sensor face. Similarly GreenSpan also offer a stainless steel nose cone (pictured left, *GreenSpan Part # 492-0246*)



### 4.2.3 BSP Filings

Brass BSP threaded adaptors can also be fitted to the MQ/MP Series Sensor (end pressure sensor configuration) for connection when monitoring pressure in process applications. (Such applications may include, pipeline monitoring, gas bubblers and tanks).

### 4.2.4 EC Sensor Shroud

Please note that MQ sensors with electrical Conductivity are fitted with the protection shroud which is calibrated in the factory with the shroud on. If the shroud is removed the calibration in water will be affected. Please ensure that the shroud is always fitted for normal use in water and only removed whilst cleaning. The shroud should be fitted when performing calibration checks in solutions.

If the sensor needs to be deployed without a shroud this requirement should be noted at time of order. The factory can then perform a special calibration without a shroud using large volumes of standard solutions. On deployment it is necessary to maintain a space of at least 100mm (4") around the head.

#### **4.2.5 Cable Options**

A standard sensor is supplied with a fixed moulded cable entry and a 7 pin Hirschman connector at the end of the cable opposite to the sensor. The length of cable is specified by the user.

#### **4.2.6 Sensor Body**

Sensor is available with a black Acetal or passivated 316 Stainless Steel body. For applications in harsh environments it is recommended that the Acetal body material be specified.

#### **4.2.7 Communication Cables**

A communication cable is required to connect the sensor to a PC.

- 5CC-840: The standard cable has a 7 socket Hirschman connector on one end and a USB on the other end. For connection to PC and laptops via USB port.
- 5CC-700: Has a 7 socket Hirschman connector on one end and DB9 on the other end. For connection to PC and laptops via serial ports.
- 5CC-750: Has a 7 socket Hirschman connector on one end and bare wires on the other end. For connection to TLC, dataloggers etc.
- 5CC-102: Has a 9 pin Conxall to D connector for serial ports. To connect a sensor with battery pack only to a PC or laptop via a serial port.

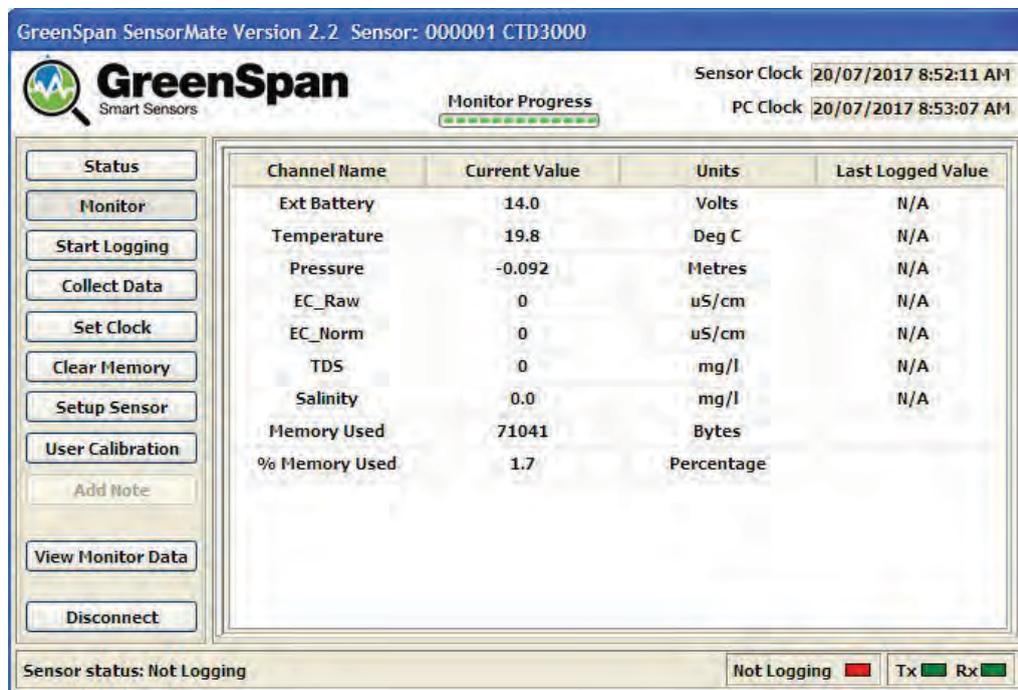
#### 4.2.8 OpKonal Serial Output – SDI Adapter Unit

The MQ/MP Series Sensor provides on board data logging of all data and serial output via RS232 to a Laptop or PC using the supplied *SensorMate* software.



A feature of the sensor is the ability to also provide serial output in SDI12 format using a small SDI Adapter unit connected to the end of the sensor cable. The SDI12 Adapter unit (*Part No 7SDI-1000*) provides a standard 3 wire SDI12 output for connection to a thirdparty Data Logger or Process Controller. The MQ/MP Series Sensor can simultaneously provide on-board data logging, as well as act as a standard SDI12 sensor.

When data is requested via SDI-12 the sensor will wake up and take a new set of readings for all channels that are enabled in the sensor. The sensor will then go into a low power, sleep mode. The user can enable or disable channels using *SensorMate*.



Channel Name	Current Value	Units	Last Logged Value
Ext Battery	14.0	Volts	N/A
Temperature	19.8	Deg C	N/A
Pressure	-0.092	Metres	N/A
EC_Raw	0	uS/cm	N/A
EC_Norm	0	uS/cm	N/A
TDS	0	mg/l	N/A
Salinity	0.0	mg/l	N/A
Memory Used	71041	Bytes	
% Memory Used	1.7	Percentage	

The easiest way to confirm which channels are enabled and what order the data will be returned via SDI-12 is to view the *SensorMate* monitor screen. By default, the data returned via SDI-12 will be the same channels and in the same order as what is displayed in the *SensorMate* monitor screen. Special SDI-12 commands allow the user to setup the SDI-12 to suit their application, which include changing the output order, how many numerals after the decimal point is returned and activate the Turbidity wiper (See SDI-1000 user manual for detail).

**NOTE:** Memory Used and Memory Used % is not returned via SDI-12.

### 4.3 On Board Battery Housing

The MQ/MP Series Sensor may be factory fitted with a non-rechargeable long-life battery pack. This enables the sensor to be deployed at remote sites completely independent of above surface power supplies (no cable connection) and allows for discreet applications.

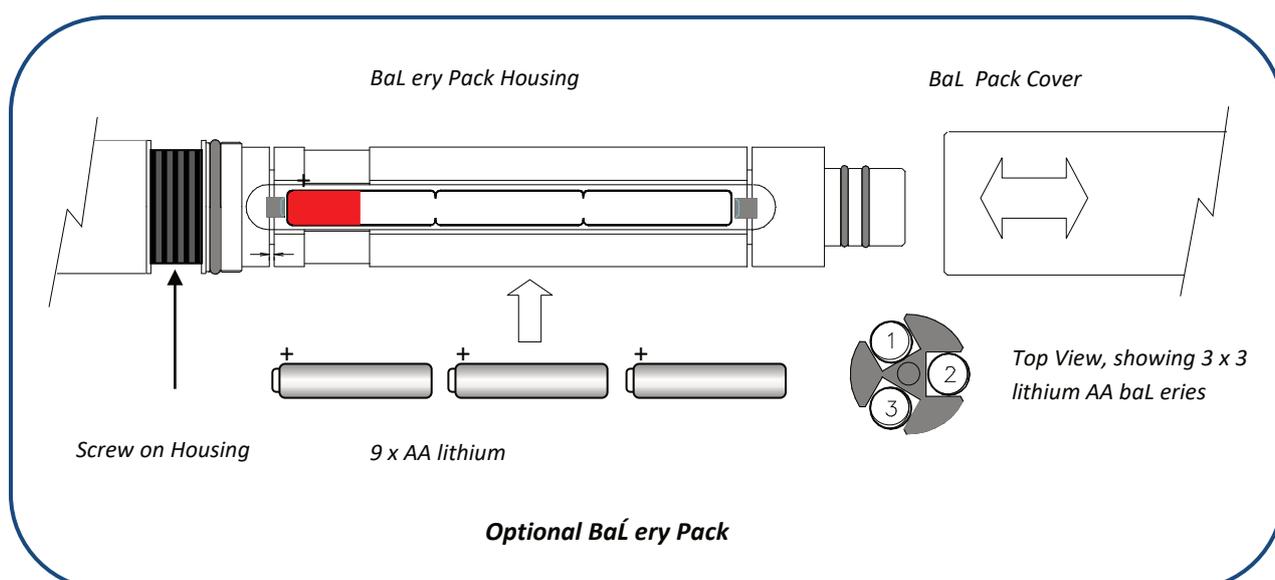
It also functions as a backup power supply in the event of a surface disturbance to the main supply. The unit is designed to allow easy access to the battery compartments for battery changeover and is housed in a cylindrical body of approximately the same dimensions as the sensor housing, thus doubling the length of the sensor.



#### 4.3.1 Battery Replacement

Batteries are removed by unscrewing the housing cover, as indicated below and gently levering the battery cells until they slip out. Replacement batteries must be inserted correctly or damage to batteries may occur. Align the +ve on the battery cells with the red indicator on the housing and push batteries in. Batteries are subject to leakage after depletion. The leakage is Thionyl Chloride, a toxic, corrosive non-flammable liquid that can cause damage to equipment and personal injury if in contact with the skin or eyes. Please replace batteries when depleted.

When installing replacement batteries within the battery housing it is necessary to push firmly on the cover until it clicks home over the O rings, after this it can be easily tightened on the thread by



hand.

#### **4.3.2 Important Battery Information**

The type of battery used in the battery pack is Li/MnO<sub>2</sub>, Lithium Thionyl Chloride 3.6V AA cells. A total of nine batteries are required for each sensor battery pack. This configuration supplies a maximum 10.8 volts at 5.2A/Hr and a useful field life, depending on sensor type and logging frequency, of up to 12 months.

**Replacement batteries are available from Aquamonix.**

**Note:** Standard AA lithium batteries (Duracell or Energiser Type) are NOT suitable for use in the sensor.

#### **4.3.3 Battery Warnings:**

- Do not dispose of batteries in fire, dispose of in appropriate manner.
- Do not short circuit
- Do not expose to water
- Do not crush or puncture
- Do not charge
- Do not over-discharge

To maintain the maximum possible life of the cells before replacement it is strongly recommended that an external power supply is connected to the sensor when downloading data. The power drawn when downloading is at its greatest level, therefore battery depletion will be much more rapid.

Battery life will depend on the battery type as well as the frequency of logging. Connection to a computer will drain the battery supply more quickly due to the higher current imposed by the RS232 serial data communications and will considerably reduce battery life. An additional internal lithium battery maintains logger data at all times but does not sustain the logging state. This battery is not user accessible and will maintain data for up to 10 years.

If the sensor is fitted with on board internal battery pack option and is to be placed in storage it is recommended that the logger be powered down and lithium batteries in the battery pack be removed. To turn off the logger after exiting from SensorMate, disconnect the communications cable and unscrew the battery cover. This exposes the battery compartment to allow removal of the batteries. Removing power will not affect any data remaining in storage so sensors could be downloaded away from the site if required.

## 4.4 Sensor Factory Calibration

### Pressure & EC Sensors:

- The sensor is assembled and calibrated to the required range using Ruska Digital Pressure controllers which are externally calibrated in NATA certified laboratories.
- Any sensor with EC or pressure parameters is placed in an environmental chamber and subjected to a matrix of temperature and pressure and EC inputs. A typical calibration collects data for each individual sensor at 6 pressure inputs (0, 20, 40, 60, 80, and 100 %FS) and 11 EC inputs (0, 10, 20, 30, 40, 50, 60, 70, 80, 90 and 100 %FS) at 6 temperatures (0, 10, 20, 30, 40 and 50 deg C).
- A unique calibration curve, for the transducers and electronics set, is calculated from this data and loaded into the sensor.
- The sensor is then re-run through the environmental chamber to ensure that the calibration curves are correct over the entire working range and the sensor meets specifications

### pH Sensors:

- Sensors are calibrated using a stable, precision DC source.
- The sensor with electrode fitted is checked in pH 4.0, 6.0 & 10.0 buffer solutions which are verified against external pH buffer solutions checked in a NATA accredited facility.

### ORP Sensors:

- Sensors are calibrated using a stable, precision DC source.
- The sensor with electrode fitted is checked in Zo Bells Standard solution

### Optical DO Sensors:

- Sensors are calibrated in an aerated DI water bath for 100% saturated and an aqueous Sodium Sulphate solution for zero.

### Turbidity Sensors:

- Sensors are calibrated using AMCO CLEAR® TURBIDITY STANDARD, for ANALITE ISO 7027 PROBES.

### All Sensors:

- An extensive range of final calibration and inspection tests, including tests in solutions of known standards, are carried out on every sensor.
- The sensor is visually inspected and packed ready for despatch.
- The complete calibration records, sensor history and batch number are placed on file and archived.
- The sensor is visually inspected and packed ready for despatch.

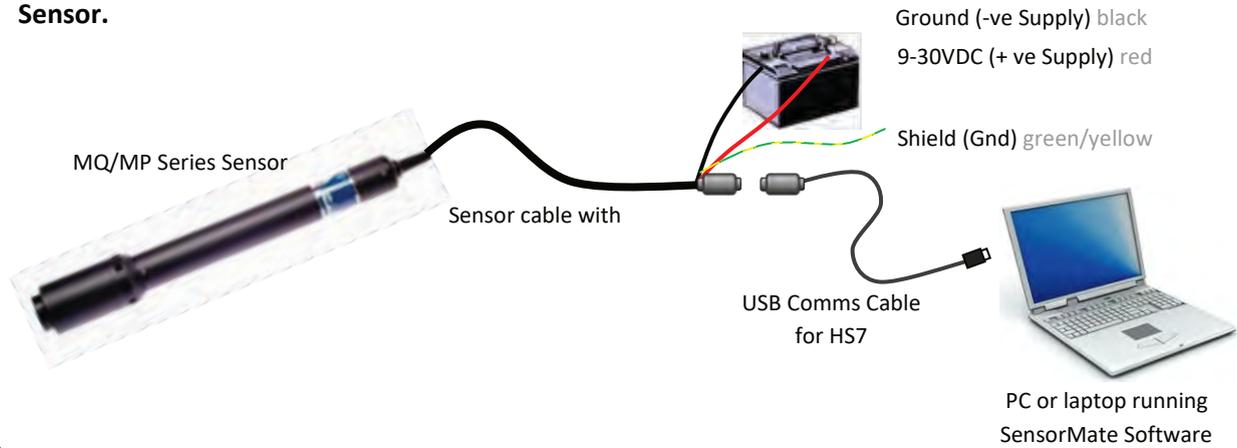
## 5 Sensor Wiring & Connections

### 5.1 Standard Connections

The MQ/MP Series sensors are designed as a self-contained data logging sensor. It is normally powered by a 12-24V DC power supply – which can be battery solar or Mains Plug Pack.

The logger has a large memory capacity and can operate for long periods between field visits. Typically the logged data is collected via laptop using the supplied SensorMate software.

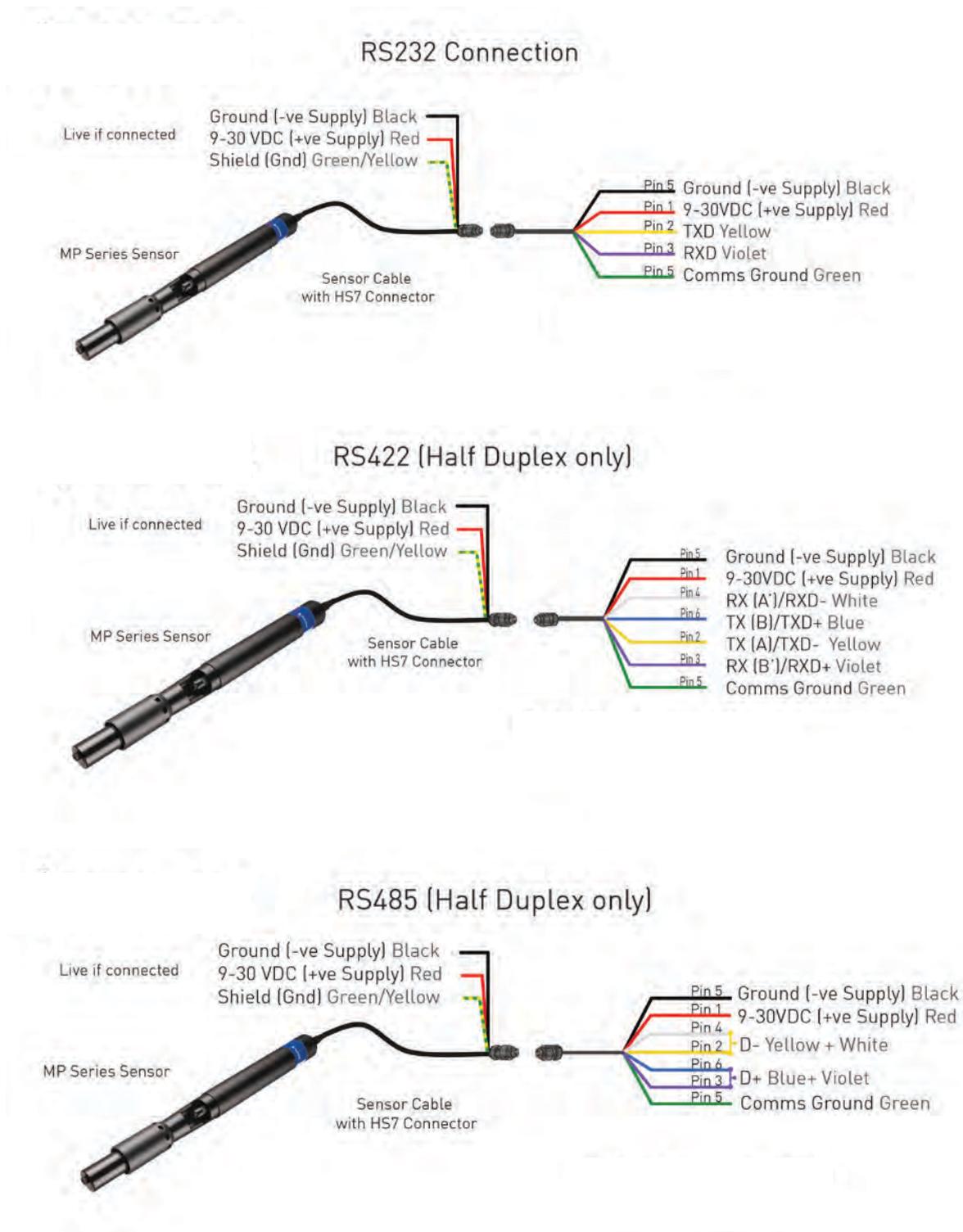
**The following diagram illustrates the typical wiring arrangement for the MQ/MP Series Sensor.**



The SensorMate software provides for configuration of the data logger, collection of logged data, and all other functions. For further information, please refer to the SensorMate User Manual.

## 5.2 Wiring Diagrams

A Breakout Communication Cable is available if a bare wire connection is more suitable for an application. The GreenSpan MQ/MP Sensor CommsMode Utility contains wiring information for the various modes of serial communication.



## 6 Serial Communication (RS232, RS422/485)

Communication to the MQ/MP series sensors is via a serial link. The user can select RS232 (default setting) or RS422/485. The GreenSpan MQ/MP Sensor Comms Mode Utility is a software tool that provides a simple method for communication modes, non-standard baud rates and Modbus settings.

	Function	5CC-750 Wire Colour
RS232	Ground (-ve Supply)	Black
	9-30 VDC (+ve Supply)	Red
	TxD	Yellow
	RxD	Violet
	Comms Ground	Green
RS422 Half Duplex	Ground (-ve Supply)	Black
	9-30 VDC (+ve Supply)	Red
	Rx (A')/RxD-	White
	TX (B)/TxD+	Blue
	Tx (A)/TxD-	Yellow
	Rx (B')RxD+	Violet
	Comms Ground	Green
RS485 Half Duplex	Ground (-ve Supply)	Black
	9-30 VDC (+ve Supply)	Red
	D-	Yellow + White
	D+	Blue + Violet
	Comms Ground	Green

**NOTE:** Full Duplex, where data is sent and received at the same time, is not supported.

## 6.1 Waking sensor

MQ/MP Sensors are designed to wake on receiving any commands on its communication lines. Although it wakes quickly, it may miss the first few characters of a command. Most generic Modbus communication programs will re-try if no valid response is received so this usually causes no problems. All in house programs send a “Null” command to wake the sensor prior to any subsequent commands.

Communication circuits will switch to a low powered, listening mode (sleep) if there has been no communication activity for 60 seconds.

## 7 Field Deployment Considerations

For applications in harsh environments it is recommended that the Optional Acetal casing be specified.

The sensor head should be periodically inspected for fouling, and can be cleaned with fresh water and damp cloth. In marine environments crustaceans may need removal at regular intervals.

The body should always be fully immersed under the water to ensure the electronic module is at water temperature and to avoid any possible anodic/cathodic action taking place on the stainless body due to the oxygen difference across the boundary.

Care should be taken if clamps are to be attached to the Stainless Steel body as the depletion of oxygen to the clamp/probe interface can cause corrosion due to anodic/cathodic action. It is recommended that Acetal body sensors be used if clamping.

Sensors should generally be installed such that they can be easily and safely removed for cleaning, servicing. For environmental applications the sensor can be mounted inside a section of PVC or steel pipe which enters the water body. The sensor can then be slid down inside the pipe until the sensor head just protrudes into the water body. This provides a high degree of protection for the sensor from environmental (sunlight, heat, flood debris etc) as well as from other influence such as vandalism etc. Most sediment transport occurs during storm events and flood conditions. Protection from floating debris damage is an important consideration along with adequate tethering of sensors.



The MQ/MP sensor (with pH or ORP) is shipped with a rubber cap covering the electrode. This cap contains a small amount of 3M KCl solution and is in place to prevent the electrode from drying out during shipping and storage. **This cap must be removed prior to installation.** The cap should be retained so that it can be placed back on the electrode if the sensor is to be removed.

### 7.1 Cabling Considerations

Care should be taken with Installation and field servicing to ensure the cable is not subjected to persistent pulling snagging or severe compression. Cyclic loading of the cable should also be avoided through careful sensor deployment. Additional wells or mounting brackets may be required to prevent sensor movement which may cause long term cable movement. Where cable runs are required which may be subject to environmental effects (heat, water movement, sunlight, flood debris etc.) it is advisable to protect the sensor cable inside a slightly larger diameter conduit such as PVC, steel or polyethylene. This also allows the sensor cable to be pulled out – should a sensor change-over be required at the site. Maximum cable runs up to several hundred meters are possible without affecting electrical signals.

## 7.2 Typical Sensor Installations

- Edge of river/stream/lake embankment.
- Mounted within a well off stream from main flow.
- Mounted within drainage channels/pipes.
- Suspended from dam walls.
- Sensor anchored to bed of lake/stream.

## 7.3 Field Installation must ensure:

- The sensor is anchored or held in position or located so it is not subject to any movement during normal operations.
- Sensor is protected from direct sunlight to avoid high temperature fluctuation
- Sensor is protected against high turbulence and possible debris loading during flow events

## 7.4 Other Considerations

Environmental compatibility should be checked before using the sensors and advice sought from GreenSpan if any doubt exists. The sensor utilises some 316 stainless components that are suitable in a majority of situations but care should be taken against possible corrosion in high Chloride, Sulphate or Ferric solutions. The body should always be totally immersed under the water to ensure that the sensor is at water temperature and to also avoid any possible anodic/cathodic action taking place on the components at the water-air interface. If using clamps to mount the sensor –these should be of a type that evenly clamps the sensor body without excessive loading that could damage the sensor body.

## 8 Maintenance (by Parameter)

### 8.1 Pressure

On a MP47 sensor, the pressure parameter will be either an inline or an end sensor. On a MQ65 sensor, the pressure parameter will be fitted inside the sensor (where the pH electrode is also housed), an inline sensor or an end sensor.

The sensor may be cleaned using a soft cloth, mild detergents and warm water. If the sensor shows signs of marine growth a light biocide can be used to clean and kill any biological growth on the sensor.

### 8.2 Electrical Conductivity

On both the MP47 and MQ65 sensor, the EC parameter will either be an inline or an end sensor.

The sensor may be cleaned using a soft cloth, mild detergents and warm water. If the sensor shows signs of marine growth a light biocide can be used to clean and kill any biological growth on the sensor.

### 8.3 pH

On a MP47 sensor, the pH parameter will be either an inline or an end sensor. On a MQ65 sensor, the pH parameter will be fitted inside the sensor mount as an inline sensor or an end sensor.

The sensor and electrode may be cleaned using a soft cloth, mild detergents and warm water. If the sensor shows signs of marine growth a light biocide can be used to clean and kill any biological growth on the sensor. Sensors are supplied with a removable shroud that provides added protection for the electrode. This shroud unscrews for cleaning.



The sensor must be cleaned with the electrode in place. The sensor will be damaged by the ingress of water or other solutions into the electrode cavity. The electrode should only be removed when it is to be replaced. To assist in cleaning the glass electrode, the sensor is provided with a special tool. A few drops of a mild detergent can be placed in the cleaning tool which is then pushed over the glass pH bulb. Carefully rotating the tool by hand should

remove most contamination. For heavy scaling or contamination a cleaner that contains some abrasive can be used. Rinse the electrode in clean water prior to installing sensor or checking calibration.

### 8.3.1 Replacing Reference Protection Ring



The reference protection ring can be removed and/or replaced (with the electrode still in place in the sensor) by unscrewing the plastic shroud on the end of the electrode. The white protection ring can be slid off the glass electrode.

### 8.3.2 Electrode storage



PH electrodes should be stored in such a way to prevent the electrode from drying out. A rubber cap is provided with the electrode for this purpose. A small amount of liquid should be placed in this cap prior to the cap being placed over the electrode. 3M KCl is the preferred storage solution however; tap water should be used if not available. Soaking in pH 4 buffer solution overnight may restore some electrodes that have been allowed to dry out,

although some calibration drift can be expected until the electrode is fully re-hydrated.

### 8.3.3 Electrode replacement

PH electrodes will require periodic replacement. How long they last is dependent on the environment and to a lesser extent the cleaning and maintenance. In a typical environment, electrode life between 1 and 3 years is quite possible. The electrode is sealed in its mount with 2 O-rings on the electrode body. The electrode is removed by unscrewing it from the housing. Spanner flats are machined on the electrode to assist.



Take care when handling the pH electrode, that it is not handled by the gold contacts. Contamination of this area may degrade the performance and expected life of the electrode

Prior to removal of an electrode the sensor must be thoroughly cleaned and dried. Care must be exercised to ensure that no liquids or other contaminants enter the electrode cavity. The pH sensor should not be stored or transported without an electrode. Immersion of a PH3000 without an electrode will likely cause damage to the sensor.

With the old electrode removed the electrode cavity should be carefully inspected. A small ring of contamination may be present at the mouth of the cavity. If present, this contamination should be removed with a clean cloth in such a way so that the contamination is not pushed inside the cavity. Do not flush the cavity with water or other cleaning solvents as damage to the electronics inside the sensor could occur.

Once clean, a new electrode can be screwed into the electrode mount. It is recommended that the calibration of the new electrode be checked prior to re-deployment.



#### 8.4 ORP (Oxygen Reduction Potential)

On a MP47 sensor, the ORP parameter will be either an inline or an end sensor. On a MQ65 sensor, the ORP parameter will be fitted inside the sensor mount as an inline sensor or an end sensor.



The sensor may be cleaned using a soft cloth, mild detergents and warm water. If the sensor shows signs of marine growth a light biocide can be used to clean and kill any biological growth on the sensor. Sensors are supplied with a removable shroud that provides added protection for the electrode. This shroud unscrews for cleaning.

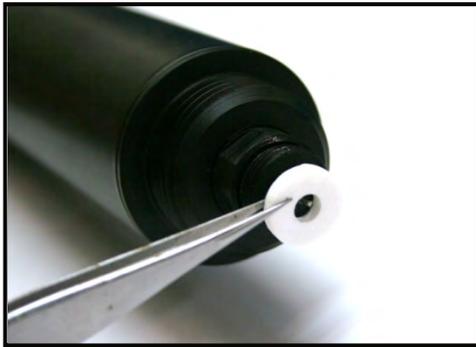
**The sensor must be cleaned with the electrode in place.** The sensor will be damaged by the ingress of water or other solutions into the electrode cavity. The electrode should only be removed when it is to be replaced. Cleanliness of the sensor and junction is critical for accurate measurement. Drip and slow response is often due to unclean sensor electrodes and reference junction. **DO NOT** use abrasive materials.

**To remove inorganic deposits and scale:** Soak sensor electrode in dilute KCl for an hour. Wash well with water and condition in 20% KCl solution before use.

**To remove solids and organics** Wipe the sensor electrode with cotton or tissue soaked in mild non-alkaline detergent. Wash with water and condition in 20% KCl before use.

**To remove plated metals from ORP Tips** Soak the tip in approx. 0.1M nitric acid for 15-20 minutes, followed by conditioning in 20% KCl.

#### 8.4.1 Replacing Reference Protection Ring



The reference protection ring can be removed and/or replaced (with the electrode still in place in the sensor) by unscrewing the plastic shroud on the end of the electrode. The white protection ring can be slid over the platinum electrode.

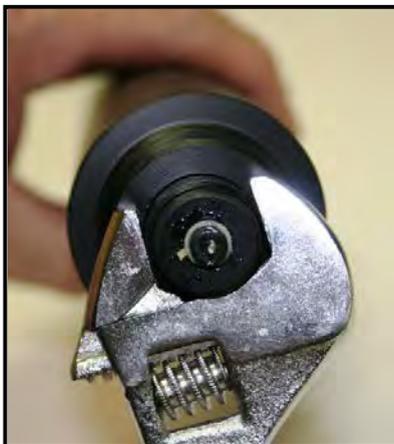
#### 8.4.2 Electrode storage



ORP electrodes should be stored in such a way to prevent the electrode from drying out. A rubber cap is provided with the electrode for this purpose. A small amount of liquid should be placed in this cap prior to the cap being placed over the electrode. 3M KCl is the preferred storage solution however; tap water should be used if not available. Soaking in 3M KCl solution overnight may restore some electrodes that have been

allowed to dry out, although some calibration drift can be expected until the electrode is fully re-hydrated.

#### 8.4.3 Electrode replacement



ORP electrodes will require periodic replacement. How long they last is dependent on the environment and to a lesser extent the cleaning and maintenance. In a typical environment, electrode life between 1 and 3 years is quite possible. The electrode is sealed in its mount with two O-rings on the electrode body. The electrode is removed by unscrewing it from the housing. Spanners are machined on the electrode to assist.

Prior to removal of an electrode the sensor must be thoroughly cleaned and dried. Care must be exercised to ensure that no liquids or other contaminants enter the electrode cavity. The ORP sensor should not be stored or transported without an electrode.

Immersion of a sensor without an electrode will likely cause damage to the sensor.

With the old electrode removed the electrode cavity should be carefully inspected. A small ring of contamination may be present at the mouth of the cavity. If present, this contamination should be removed with a clean cloth in such a way so that the contamination is not pushed inside the cavity. Do not flush the cavity with water or other cleaning solvents as damage to the electronics inside the sensor could occur.

Once clean, a new electrode can be screwed into the electrode mount. It is recommended that the calibration of the new electrode be checked prior to re-deployment

## 8.5 Turbidity

On a MP47 or MQ65 sensor, the turbidity parameter will be an end sensor only.

### 8.5.1 Wiper Replacement

The effectiveness of the wiper in maintaining a clean Optical surface will eventually be compromised, the time being dependent on the water under investigation and the number of wiping cycles carried out. We recommend periodic inspection of the wiper pad to determine if the material is deteriorating or is impregnated with material from bio-fouling.



The wiper is a consumable item. Wiper packs containing a wiper and a hex key are available as a standard accessory.

To change the wiper, loosen the set screw in the wiper arm until the wiper assembly can be removed from the wiping shaft. Place a new wiper assembly on the shaft with the set screw aligned squarely with the flange on the wiping shaft. Gently press the wiper arm down until the wiper arm hits the stop on the shaft. The wiper pad should now be compressed to roughly one half its original thickness. Tighten the set screw - do not over tighten.

**NOTE:** It is imperative that the set screw be fastened squarely aligned onto the flange on the shaft otherwise proper operation will be affected.

**CAUTION:**



Do not over tighten the set screw or manually attempt to rotate the wiper arm once set onto the shaft. Any attempt to manually rotate the wiper may cause gearbox damage and void the warranty.

## 8.6 Optical Dissolved Oxygen

On a MP47 or MQ65 sensor, the ODO parameter will be an end sensor only.

The sensor and electrode may be cleaned using a soft cloth, mild detergents and warm water. If the sensor shows signs of marine growth a light biocide can be used to clean and kill any biological growth on the sensor. It is important to take care when cleaning around the sensor optics – do not scratch the sensor lens.

The sensor will be damaged by the ingress of water or other solutions into the electronics cavity and Warranty will be voided if disassembled. Rinse the electrode in clean water prior to installing sensor or checking calibration.

## 9 User Calibration and Testing

The factory supplied Certificate of Conformance will provide detailed information regarding the sensor ranges and specifications; this document should be retained for future reference.

### 9.1 Pressure Sensors

To maintain high quality control over monitoring programs, it is recommended that pressure calibration is checked every 3-6 months. If re-calibration is required a method is presented here using standard methods. Alternatively sensors may be returned to an authorised GreenSpan agent for re-calibration.

The sensor can be checked by use of known pressure inputs, usually from an accurate digital pressure calibrator or dead weight tester. However a quick check can be done at any time by reading the sensor in air.

#### Quick Check method for a gauge pressure sensor:

1. Remove the sensor from the water, ensure the sensor is clean and dry and the vent tube at the top of the cable is not sealed.
2. Connect the sensor to a PC and run SensorMate.
3. Once connected the monitor screen will display the readings. The Pressure value should read Zero +/- 0.1% of the full scale range of the sensor.
4. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 0.1 % FS.

#### Quick Check method for an absolute pressure sensor:

1. Remove the sensor from the water, ensure the sensor is clean and dry.
2. Connect the sensor to a PC and run SensorMate.
3. Obtain the barometric pressure for the location \* where the check is being performed.
4. Once connected the monitor screen will display the readings. The Pressure value should read the barometric pressure +/- 0.1% of the full scale range of the sensor. (1hPa = 0.010216 m H<sub>2</sub>O @ 20°C)
5. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 0.1 % FS.

\* The accuracy and calibration of the barometer should be considered when making the comparison.

### Re-Calibration Method Using Digital Pressure Calibrator or Dead Weight Tester:

1. Ensure the sensor is clean and dry.
2. Connect the sensor to the calibrator using an appropriate BSP fitting.
3. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
4. Run SensorMate
5. In SensorMate, select User calibration from the SensorMate main menu.
6. Select the Pressure Channel.
7. Select 2 point Span and Offset Calibration Type.
8. Apply the low pressure input to the sensor from the calibrator. Typically this will be zero for a gauge sensor.
9. The screen should display a window to allow entry of the new low value, type in the new value to be read by the Sensor for zero, e.g.: (0000.00), click OK.
10. Apply the high pressure input to the sensor from the calibrator. Typically this will be full scale for a gauge sensor.
11. The screen should display a window to allow entry of the new high value, type in the new value to be read by the Sensor for the high value, e.g.: (0005.00), If the calibrator cannot set an output in m of water a conversion will need to be calculated and entered, click OK.
12. Refer to the SensorMate User Manual for further reference.

**NOTE:** Absolute pressures must be set and entered when calibrating an absolute sensor

## 9.2 Electrical Conductivity

To maintain high quality control over monitoring programs, it is recommended EC calibration is checked at least every 3-6 months. If re-calibration is required a method is presented here using GreenSpan EC Calibrators and using Standard solutions. Alternatively sensors may be returned to an authorised GreenSpan agent for re-calibration.

### Quick Check Method:

The following procedures detail a quick method to check the calibration for both full-scale and zero using the supplied loop calibrator.

**NOTE:** For new EC sensors each calibrator is clearly marked with a serial number and non-normalised calibration value.

1. Remove the sensor from the water, unscrew the shroud and dry the EC head and temperature button.
2. Connect the sensor to a PC and run SensorMate.
3. Once connected the monitor screen will display the readings. The EC value should read Zero +/- 1% of the full scale range of the sensor.
4. Place the loop calibrator through the hole in the EC head and plug the connector together.

5. The non-normalised EC value should read the value marked on the loop calibrator +/- 1% of the full scale range of the sensor.
6. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 1 % FS.

#### **Re-Calibration Method using the EC loop calibrator:**

While the EC sensor is designed for long term stability it is normal for any electronics to experience some drift over time. If re-calibration is required -

1. Remove the shroud and ensure the sensor is clean and dry.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. In SensorMate, select User Calibration from the SensorMate main menu.
5. Select the EC Channel.
6. Select 2 point Span and Offset Calibration Type.
7. The zero value is read in SensorMate **without** the loop calibrator. The screen should display a window to allow entry of the new low value, type in the new value to be read by the sensor for zero, eg: (0000.00) click OK.
8. Loop the EC calibrator wire through the EC head and connect together.
9. Enter the value marked on the loop calibrator, click OK.

#### **Re-Calibration Method Using EC Calibration Solutions:**

The sensor can be checked by use of known laboratory conductivity standards, a thermometer and/or a third party EC sensor.

1. Ensure the sensor is clean and dry (the shroud should be fitted)
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. In SensorMate, select User Calibration from the SensorMate main menu.
5. Select the EC Channel.
6. Select 2 point Span and Offset Calibration Type.
7. The zero value is read in air. The screen should display a window to allow entry of the new low value, type in the new value to be read by the Sensor for zero, eg: (0000.00) click OK.
8. Submerge the sensor in full scale calibration standard. The sensor should be gently agitated to remove any air bubbles. Allow the temperature of the solution and sensor to stabilize (recommend at least 1 hour).
9. Enter the non-normalised EC value of the standard solution, click OK.
10. Refer to the SensorMate User Manual for further reference.

### 9.3 pH

To maintain high quality control over monitoring programs, it is recommended pH calibration is checked every 3-6 months.

The sensor can be checked by use of known pH standards (buffer solutions). Alternatively sensors may be returned to an authorised GreenSpan agent for re-calibration.

#### Quick Check Method: pH Sensors

1. Remove the sensor from the water, ensure the sensor is clean and dry. Dirty electrodes could be a key source of calibration errors.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. Place the sensor in a low level pH buffer (eg. pH 4) so that the electrode is fully submerged.
5. Once connected the monitor screen will display the readings. The pH value displayed on the monitor screen should be the pH buffer value +/- 1% of the full scale range of the sensor.
6. Carefully rinse the electrode in water and shake off any attached droplets.
7. Place the sensor in a high level pH buffer (e.g. pH 10) so that the electrode is fully submerged. Record the measured output value.
8. The pH value displayed on the monitor screen should be the pH buffer value +/- 1% of the full scale range of the sensor.
9. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 1 % FS.

#### Re-Calibration Method using pH Buffer Solutions:

1. Ensure the sensor is clean and dry.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. In SensorMate, select User Calibration from the SensorMate main menu.
5. Select the pH Channel.
6. Select 2 point Span and Offset Calibration Type.
7. Put the sensor in a solution with a known, low pH (ie. pH buffer). Allow time for the electrode to stabilize.
8. The screen should display a window to allow entry of the new low value, type in the value of the low pH buffer eg: (0004.00), click OK.

9. Put the sensor in a solution with a known, high pH (ie. pH buffer). Allow time for the electrode to stabilize.
10. The screen should display a window to allow entry of the new high value, type in the value of the high pH buffer, eg: (0010.00), click OK
11. Refer to the SensorMate User Manual for further reference.

## 9.4 ORP

It is not possible to calibrate Eh electrodes over a range of redox potentials (as is done with pH electrodes). Instead standard solutions that are stable with known redox potentials for specific indicator electrodes are used to check response.

There are two main solutions used for measuring redox potentials, Light's solution and Zo Bell's solution.

The table below shows the theoretical potential of Platinum ORP electrodes using two different common reference electrodes in the ORP standard Light's solution and Zo Bell's solution. The actual potential of the GreenSpan ORP electrode in Light's solution is specified as 465mV $\pm$  10mV.

### Comparison Table

Reference	Standard Hydrogen Electrode (SHE)	GreenSpan Ag/AgCl Electrode
Light's solution	+675mV	+465mV, $\pm$ 10mV
ZoBell's Solution	-	+229mV Saturated KCL

If the readings obtained are outside the expected values the electrode should be cleaned and/or replaced. Sensors may be returned to an authorised GreenSpan agent for re-calibration.

### Quick Check Method:

1. Remove the sensor from the water; ensure the sensor is clean. Dirty electrodes could be a key source of calibration errors.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. Place the sensor in a standard solution so that the electrode is fully submerged.
5. Once connected the monitor screen will display the readings. The ORP value displayed on the monitor screen should be the standard solution value  $\pm$  2% of the full scale range of the sensor.

### **Re-Calibration Method Using Calibration Solutions:**

1. Ensure the sensor is clean and dry.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. In SensorMate, select User Calibration from the SensorMate main menu.
5. Select the ORP Channel.
6. Select 1 point Offset Calibration Type.
7. Put the sensor in a solution with a known ORP value. Allow time for the electrode to stabilize.
8. The screen should display a window to allow entry of the new low value, type in the value of the standard solution, e.g.: (0228.00), Click OK.
9. Refer to the SensorMate User Manual for further reference.

## **9.5 Turbidity**

The sensor can be checked by use of known laboratory Turbidity standards. Sensors are calibrated using AMCO CLEAR® TURBIDITY STANDARD, for ANALITE ISO 7027 PROBES.

The claimed advantages of these standards are-

- Safe, non-toxic and disposable
- Easy-to-use/No dilutions or preparations
- Accurate to 1% lot-to-lot
- Available in a wide range of values
- Stable/does not settle out of suspension
- Guaranteed One Year Shelf Life
- N.I.S.T. Traceable

### **Quick Check Method:**

1. Remove the sensor from the water, ensure the sensor is clean and dry.
2. Place the sensor in clean water so that the sensor face is at least 50mm clear of the bottom of the container.
3. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
4. Run SensorMate.
5. Once connected the monitor screen will display the readings. The Turbidity value should read Zero +/- 3% of the full scale range of the sensor.
6. Place the sensor in a full scale Turbidity solution so that the sensor face is at least 50mm clear of the bottom of the container.
7. The Turbidity value should read +/- 3% of the full scale range of the sensor.
8. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 3 % FS.

### Re-Calibration Method Using Calibration Solutions:

1. Ensure the sensor is clean and dry.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. In SensorMate, select User Calibration from the SensorMate main menu.
5. Select the Turbidity Channel.
6. Select 2 point Span and Offset Calibration Type.
7. The zero value is read in clean filtered water. Sensor should be gently agitated to remove any air bubbles.
8. The screen should display a window to allow entry of the new low value, type in the new value to be read by the Sensor for zero, eg: (0000.00) click OK.
9. Submerge the sensor in full scale calibration standard. Sensor should be gently agitated to remove any air bubbles.
10. The screen should display a window to allow entry of the new high value, type in the new value to be read by the Sensor for the high value, eg: (0400.00) click OK.

### 9.6 ODO

To maintain high quality control over monitoring programs, it is recommended ODO calibration is checked every 3-6 months. The MQ/MP Sensor has a user calibration facility in SensorMate.

The sensor can be checked by use of known standards.

#### Quick Check Method:

1. Remove the sensor from the water, ensure the sensor is clean.
2. Provide power to the sensor, connect sensor to a PC with appropriate communication cable.
3. Run SensorMate.
4. Place the sensor into a container with Sodium Sulphite solution (2 tea spoons Sodium Sulphite per 1 litre of water) for at least 10 minutes to allow the sensor to stabilise.
5. Once connected, the monitor screen will display the readings. The DO% Sat reading displayed, should be  $\pm 1\%$  of 0% .
6. Remove the sensor from the container and rinse the sensor with clean water.
7. Place the sensor into a container of full scale solution (tap water aerated by an air pump and circulated using a water pump) and allow the sensor to stabilise for at least 10 minutes..
8. Check the reading on the monitor screen, the DO % sat should be  $\pm 1\%$  of 98%.

9. This confirms that the sensor electronics has remained stable and no further action should be required if the sensor is within +/- 1% of these readings in different conditions.

### **Re-Calibration Method Using Calibration Solutions**

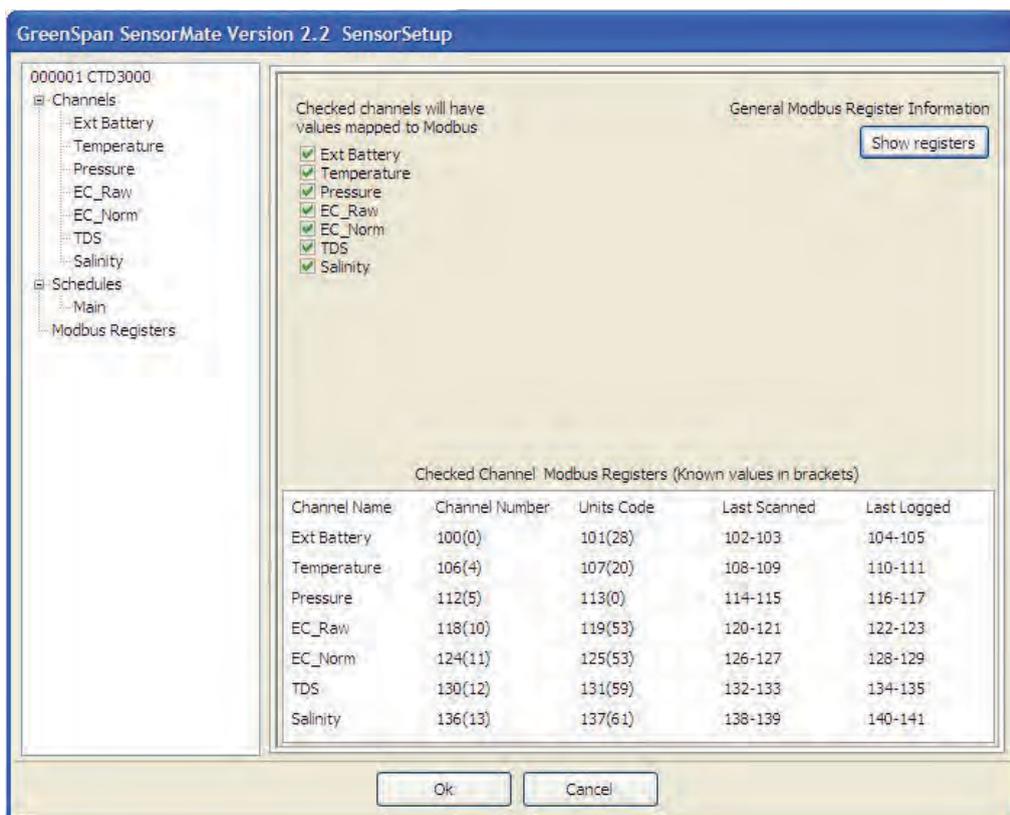
1. Ensure the sensor is clean and dry.
2. There are 2 steps to complete the calibration for an MQ/MP sensor with Optical DO:
  - the 1 Point Offset ( zero calibration) and,
  - the 1 Point Span (full scale calibration)
3. Connect the sensor with the appropriate communication cable and turn on the DC power.
4. Run SensorMate.
5. In SensorMate, select User Calibration from the SensorMate main menu.
6. Select the calibration channel – ODO
7. Perform the zero calibration by selecting 1 Point offset in the Calibration Type.
8. Place the sensor into a Sodium Sulphite solution and allow 10 minutes to stabilise. Ensure the ODO head is fully submerged.
9. Click on the Calibrate Channel button.
10. The screen should display a window to allow entry of the new low value, type in 0 and click OK once the value has been entered.
11. Remove the sensor from the container and rinse it with clean water.
12. Perform full scale calibration by selecting 1 Point Span
13. Place the sensor into an aerated full scale and allow to stabilise for at least 10 minutes. Ensure the ODO head is fully submerged.
14. Click on the Calibrate Channel button.
15. The screen should display a window to allow entry of the new high value. Enter the new value e.g. 98% for the full scale value and click OK
16. Click on Monitor to verify the readings on the screen.

## 10 Modbus notes

### 10.1 Holding Registers

Sensor information can be mapped to Modbus holding registers. This provides an easy transfer of data to the many devices that support Modbus. The user can select Modbus RTU (default) or Modbus ASCII.

SensorMate V2.1 software has a feature to assist with setting up Modbus holding registers. When “Modbus Registers” is clicked in the Sensor Setup tree, a list of available channels will be displayed with a selection box. Selecting a Sensor channel will allocate 6 holding registers for channel information. A table will update and display the holding registers allocated. The **Ok** button must be pressed to send this setup to the sensor.



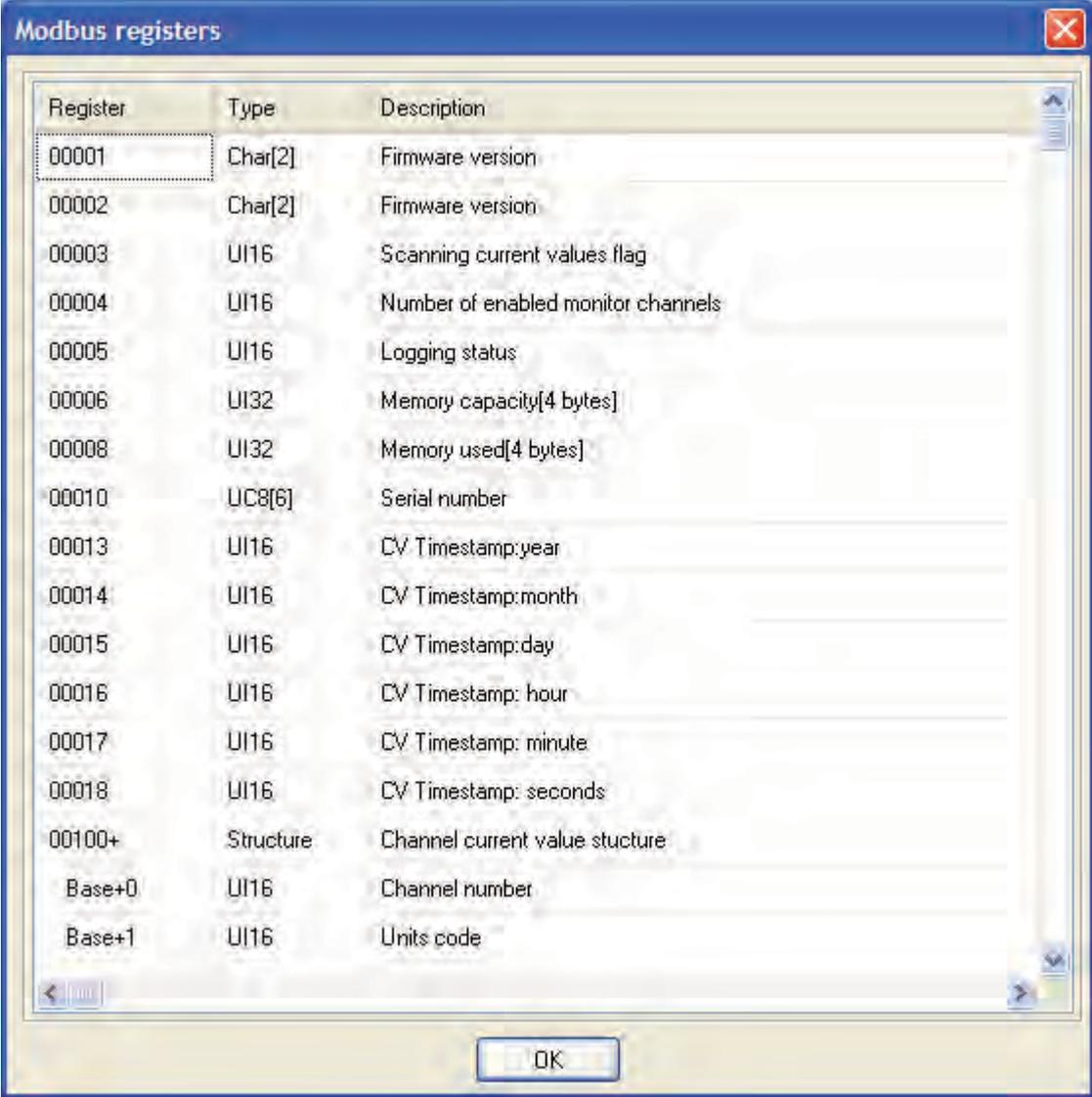
Each channel mapped to Modbus take 6 registers starting from 100 (see table below).

Address decimal	R	Type	Description
001xx + 0		UC8	Channel number
001xx + 1		UC8	Units code
001xx + 2		Float	Last Scanned Value
001xx + 4		Float	Last Logged Value

The sensor's configuration file contains the information of which channels are mapped to these Modbus registers.

## 10.2 Show registers button

There is also a "Show registers" button that provides other information that is also written to holding registers.



The screenshot shows a window titled "Modbus registers" with a table of registers. The table has three columns: "Register", "Type", and "Description". The registers listed are:

Register	Type	Description
00001	Char[2]	Firmware version
00002	Char[2]	Firmware version
00003	UI16	Scanning current values flag
00004	UI16	Number of enabled monitor channels
00005	UI16	Logging status
00006	UI32	Memory capacity[4 bytes]
00008	UI32	Memory used[4 bytes]
00010	UC8[6]	Serial number
00013	UI16	CV Timestamp:year
00014	UI16	CV Timestamp:month
00015	UI16	CV Timestamp:day
00016	UI16	CV Timestamp: hour
00017	UI16	CV Timestamp: minute
00018	UI16	CV Timestamp: seconds
00100+	Structure	Channel current value structure
Base+0	UI16	Channel number
Base+1	UI16	Units code

An "OK" button is located at the bottom center of the dialog box.

## 10.3 Codes and Terminology

The following list of codes, abbreviations and terms may be used in the software coding of these structures:

Bool	8 bit character used to represent TRUE and FALSE
UC8	Unsigned 8 bit character
UI16	unsigned 16 bit integer
SI16	signed 16 bit integer
UI32	unsigned 32 bit integer
SI32	signed 32 bit integer
F32	IEEE754 single precision floating point 32 bit value.

Cal	Calibration
Confi	Configuration
CV	Current Values
HO	High order – upper 8 bits of a 16 bit word
LO	Low order – lower 8 bits of a 16 bit word.

## 10.4 Integer and Floating Point Values

The Modbus protocol specifies that the order of bytes is sent as low order first. For example, when sending a value of 0x1234, the first byte sent is 0x12 followed by the value 0x34.

## 10.5 32 Bit Values

The Modbus registers for 32 bit integer and floating point values are aligned on even register numbers and must be read and written in a single function call. For example, to read a 32 bit value from registers 00102/00103, call function code 03, start register 00102 and read two register values. An attempt to read register 00103 will result in an exception response.

## 10.6 Floating Point

All floating-point variables (denoted as type F32) are IEEE754 Floating Point format (single precision 32 bit). Example:

Read registers 00100 and 00101: flow velocity which has a value of 51.392. The Modbus registers return 0x424d and 0x9225 from addresses 0100 and 0101. This data corresponds to 0x25924d42 (low byte first) which is the same as 51.3297. See test code below:

```

/* PC code example */
c[0] = 0x25;          /* last byte from register read */
c[1] = 0x92;
c[2] = 0x4d;
c[3] = 0x42;        /* first byte from register read */

t = *((float*) &c[0]);

print("%f", t); /* value printed is 51.392 */

```

## 10.7 Updating Register Data

As per the Modbus protocol, data contained in registers is immediately sent on request. This may mean that the data sent may not be recent. To allow the user to obtain the most current data possible, using only Modbus commands, a request for data also starts the "Get Current Values" routine in the sensor, where all parameters that are set up in the monitor screen are read.

Get Current Values for a typical MQ/MP sensor would be complete within 6 seconds (5 second warm-up time + <1 second process time). When complete the "Last Scanned Values" are updated. To get the most current data a user can read the registers, wait until the sensor has a chance to get current values, and read registers again.

Alternatively, if the sensor’s logging schedule is on, the data in the “Last Scanned Value” registers will be updated according to this schedule (e.g. if a 3 minute scan time is set, the data in the Last Scanned Value registers will be no older the 3 minutes when read).

### 10.8 Command Set – Modbus Function Codes

Func Code	Modbus Function Description	Uses for 3000 Series
03	Read Multiple registers	Read current values, calibration data, basic calibration and configuration data.
16	Write registers - Multiple	Write current values, calibration data, basic calibration data and configuration data. Initiate a scan.
65-69	User commands	See following section

### 10.9 Command Set – User Function Codes

Function Code	User Function Description	Uses for 3000 Series
65	Set Date and Time	Future use
66	Start Logging	Future use
67	Stop Logging	Clears totals, as per flags sent as command parameters.
68	Wipe now	Enter passcode to gain level 0, 1 or 2 access and to log out.
69	Read Channel Name	Returns a text string for a given channel number

### 10.10 Exception Responses

Exception Code	Description	Uses for 3000 Series
01	Illegal function	The received function code is not a valid
02	Illegal Data Address	The address in the data field is not valid
03	Illegal Data Value	The value in the data field is outside limits
05	ACK Acknowledge	The function is valid and is being processed
06	Busy, message rejected	The message was received without error but the 3000 Series cannot perform the operation. Retry later.
07	NAK	Access denied – operation cannot be performed

## 11 Specifications

PRESSURE	Measurement technique	½" Ceramic Capacitance Sensor		
	Standard Pressure ranges available	Gauge 2.5, 5, 10, 20, 40, 75, 100 m Absolute 20, 40, 75, 100 m		
	Max Over Range	4 times Full Scale range.		
	Other Ranges available	Yes – Calibration charge may apply – refer sales office		
	Overall Accuracy (combined linearity, hysteresis and repeatability)	± 0.1% Full Scale range		
	Long term stability	0.2% full scale per annum		
	Resolution	Depth – 0.001 m , Temp – 0.05°C,		
PH	Measurement Technique	Gel-filled glass electrode with internal Ag/AgCl reference; Field replaceable electrode		
	Sensor Range	0–14 pH		
	Resolution	0.001 pH		
	Accuracy	± 0.2 pH		
ORP	Measurement Technique	Platinum electrode with internal Ag/AgCl reference; Field replaceable electrode		
	Sensor Range	–1000 mV – ±1000 mV		
	Resolution	1 mV		
	Accuracy	± 2% full scale		
EC	Measurement Technique	Toroidal conductivity		
	Standard EC ranges available	0–2000 µS/cm, 0–5000 µS/cm, 0–10000 µS/cm, 0–20000 µS/cm, 0–60000 µS/cm, 0–70000 µS/cm.		
	Other Ranges are available	Yes – calibration charge may apply – refer sales office		
	Overall Accuracy (combined linearity, hysteresis and repeatability)	±1 % full scale range		
	Resolution	EC – 1 µS		
TURBIDITY	Measurement Technique	90° Infra-red (ISO7027)		
	Standard ranges available (factory set)	100 NTU,	400 NTU	1000 NTU
	Resolution	0.1 NTU	0.2 NTU	0.3 NTU
	Linearity	± 1%	± 1%	± 3%
	Temperature Coefficient	± 0.2% /°C	± 0.1% /°C	± 0.1% /°C
	Calibration Standard	APS AEPA polymer solutions 0, 100 NTU, 400 NTU, 1000 NTU		

OPTICAL DO	Measurement Technique	Oxygen fluorescence detection method
	Sensor Range	0–200% saturation (0-20 ppm)
	Resolution	0.1%,
	Accuracy	Oxygen 1% of reading or 0.02 ppm whichever is greater
Response Time	90% of DO change within 60 seconds	
TEMP	Measurement Technique	Integrated precision thermistor
	Operating ranges	0–50°C
	Overall Accuracy (combined linearity, hysteresis and repeatability)	0.2 Deg
Sensor Outputs	Internal Data Logger – serial data via SensorMate software Optional adaptor provides SDI12 serial output (3 wire)	
Storage Temperature	–5 Deg C – +60 Deg C	
Cable type	Polyurethane sheathed cable, OD 8 mm, with 3 mm vent tube, moulded entry, HS7 connector for serial connection.	
Standard Cable lengths	10, 20, 30, 50, 100, 150 m	
Non-standard Cable Lengths	Yes – (Extra cable moulding time may be required)	
Power supply	8 to 30 V DC (at sensor), or on-board battery pack (option)	
Power ESD protection	2000 volts	
Current consumption	Sleep ± 0.2 mA, logging 20 mA, communicating 30 mA (consumption rates vary depending on parameters selected)	
Sensor warm up time	Up to 5 seconds	
On-board battery pack (option)	Housing screws to sensor size (OD × L) 47 mm × 250 mm	
Battery capacity	9 × Lithium AA (3.6Volt) – Total capacity 5.2 Ah @ 10.8 v	
Typical field life (battery pack)	Over 12 month's remote operation @ 15 minute data logging.	
Internal data logger	Non-volatile, battery backed RAM with real time clock	
Memory size	4 Mb capacity, with user selectable wrap function	
Measuring units	User definable (Metric and Imperial US units)	
Data storage	250,000 readings. (Typically 5 minute data for >12 months)	
Logging frequency	User selectable from 1 second up to once per day	
Dimensions (L × OD)	MP47 – 355 mm × 47 mm (14" × 1.78"), MQ65 – 355 mm × 65 mm (14" × 2.5") –Optional End Mount Battery pack – 300 mm × 47 mm	
Weight	MP47 – 550 g plus cable weight (665g per 10m length) MQ65 – 650 g (plus cable weight (665g per 10 m length)	
Welded materials	Acetal, ceramic, polyurethane, viton	

GREENSPAN

